



CPD Legal Studio

Trends in Future Mobility

March 2020



Why 'mobility' and not 'transport'?

Mobility as a Service – Customer Focused End to End Journey Approach

Mobility and Mobility as a Service is about a customer focused end to end journey focus

The discussion and solution are no longer about singular transport modes

Making connections is key to mobility success

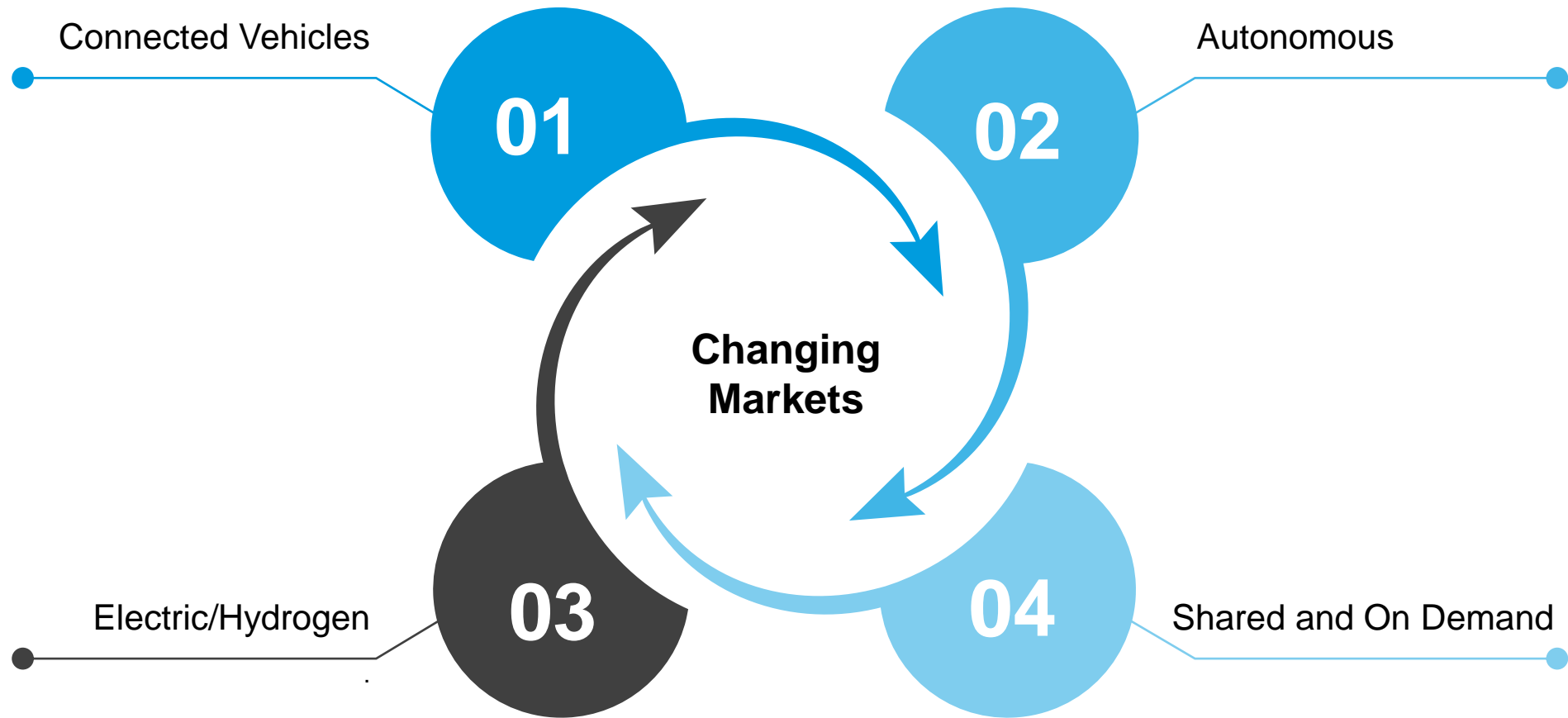
Mobility as a Service (MaaS) is emerging as an efficient way to move people and freight

MaaS will help meet the needs of the young, elderly and disabled

Transport agencies are developing solutions to provide MaaS – TfNSW Digital Accelerator launched MaaS Innovation Challenge in 2018

“The vision for TfNSW is to enable a vibrant, open mobility marketplace where providers compete to best meet community & customer needs with compelling alternatives to car ownership”

Transport Trends

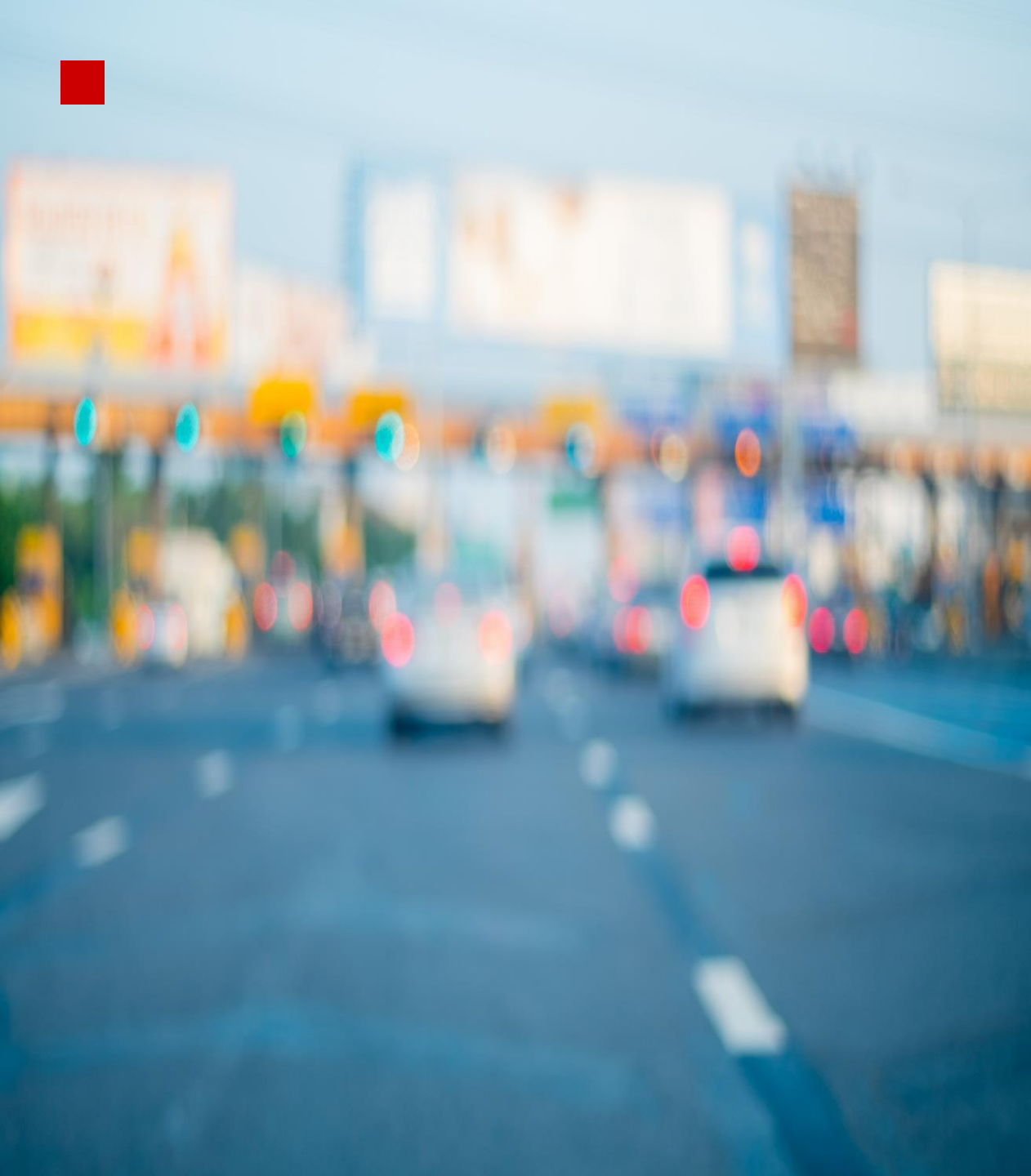


NSW future mobility ecosystem



NSW Future Mobility Prospectus





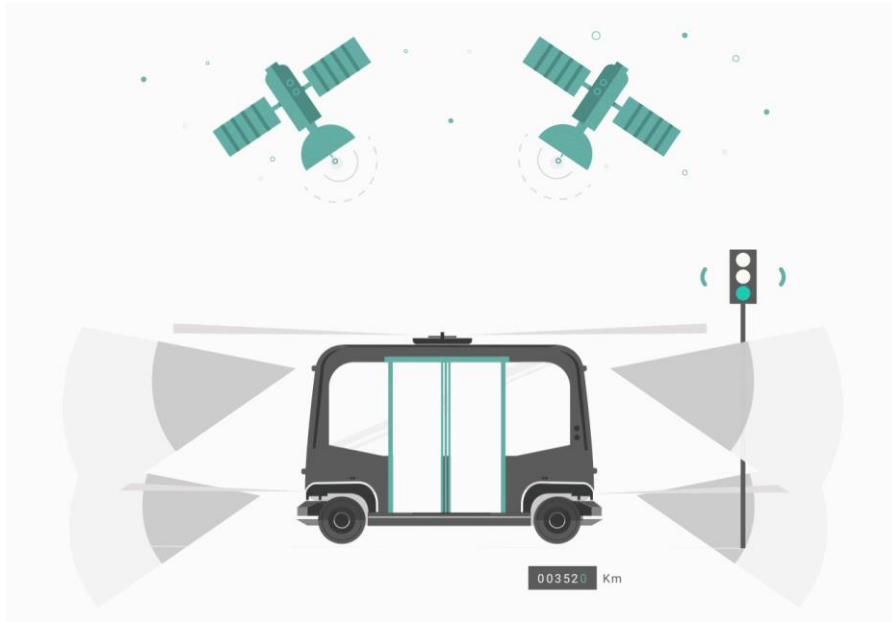
What's new in connected and driverless mobility development?

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Autonomous Uber and LEAP

In Pittsburg, PA, Uber are developing its fleet of autonomous Volvos – currently in trial on public streets

The autonomous Linden LEAP serving a roughly 3-mile route and first-mile/last-mile solution to connect residents to community resources



3D Printed Autonomous Vehicles

Local Motors

Olli Autonomous 3D Printed Bus



Autonomous Trucks & Platooning

Cab-less and autonomous, fully electric truck in commercial operations on public road – Sweden

Modular self-driving electric autonomous shipping vehicles for logistics
Autonomous platoon trials



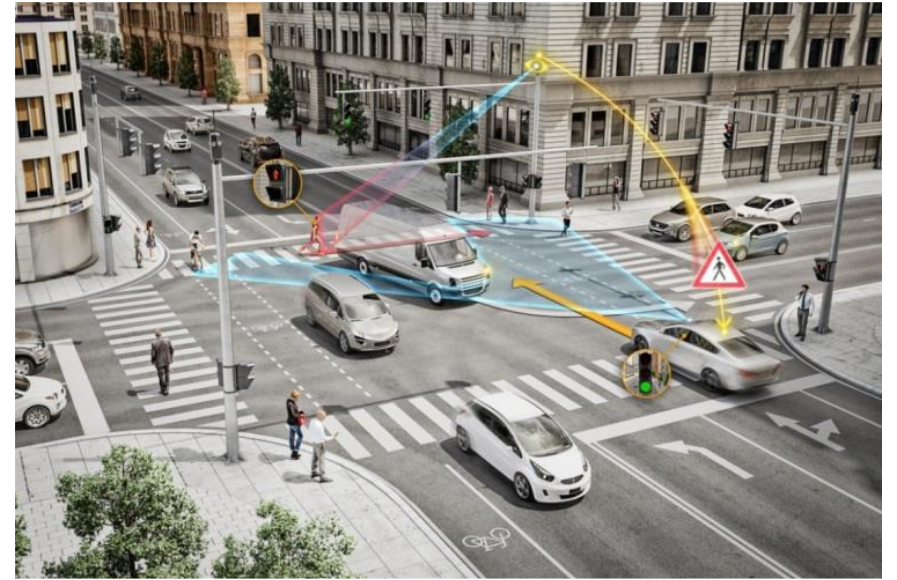
Surtrac and AI

**Artificial intelligence traffic control is being trialled in Pittsburg
Developing and deploying the technology to keep the traffic
flowing took a team of researchers and roboticists from Carnegie
Mellon University together with the help of city engineers and
funding from foundations**

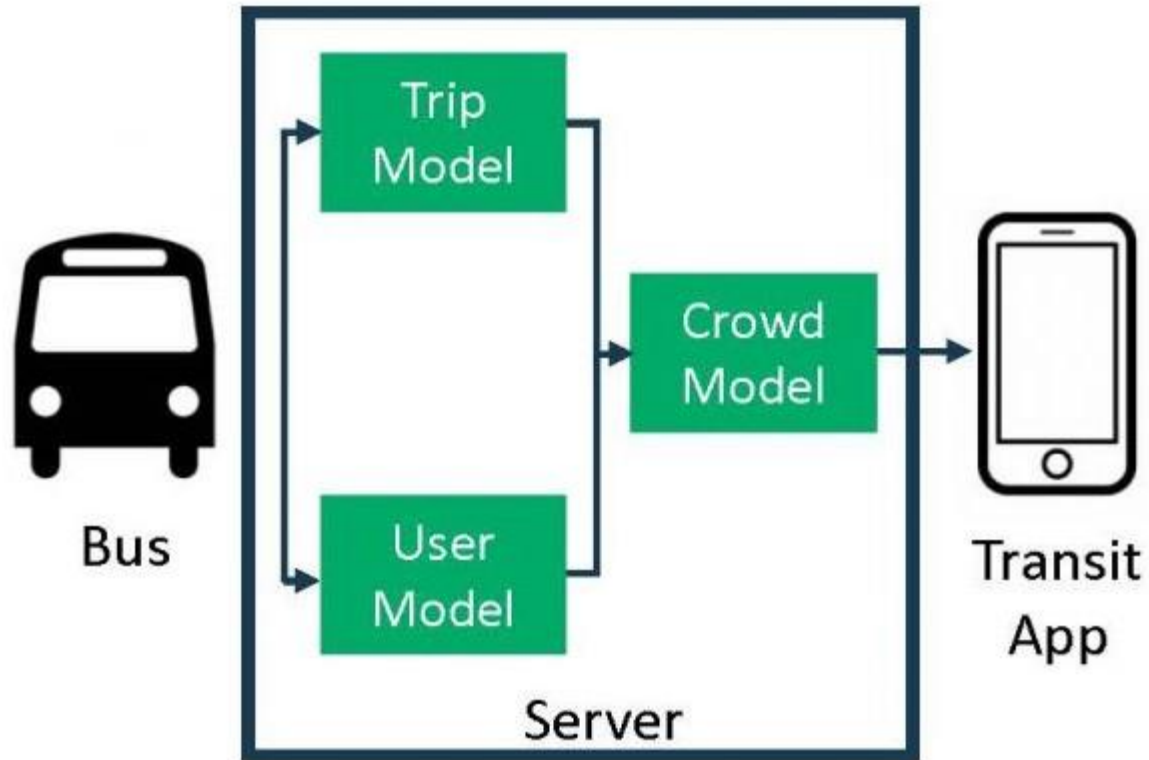
Surtrac is a real time signal control system developed at Carnegie Mellon University that reduces travel times, emissions and supports economic opportunity and quality of life

The Software allows the signals to “talk to each other.” Each signal makes its own decisions on timing by sensing approaching traffic streams and generating a timing plan to optimize movement through intersections. The signals then share plans with neighbouring signals to create coordinated actions

The system also connects to cyclists and pedestrians through phone apps and wearable devices that are also designed for people with vision impairment and disabilities



Real Time Detection of Crowded Buses via Mobile Phones



Accurate knowledge about the utilization of public transit vehicles by riders, such as bus fullness, is critical information for public transit planners.

Automatic Passenger Counter (APC) information is used by transit planners to detect transit bottlenecks, assess overcrowding of vehicles, and provide rider experience. APC data may be a good measure of rider counts but can suffer from high error when considering individual due to compounding errors.

The purpose of this research is to investigate a new technique for recording information about bus vehicle fullness using participatory sensing, via a user's smartphone accelerometer and GPS.

Autonomous Vehicle Test Tracks



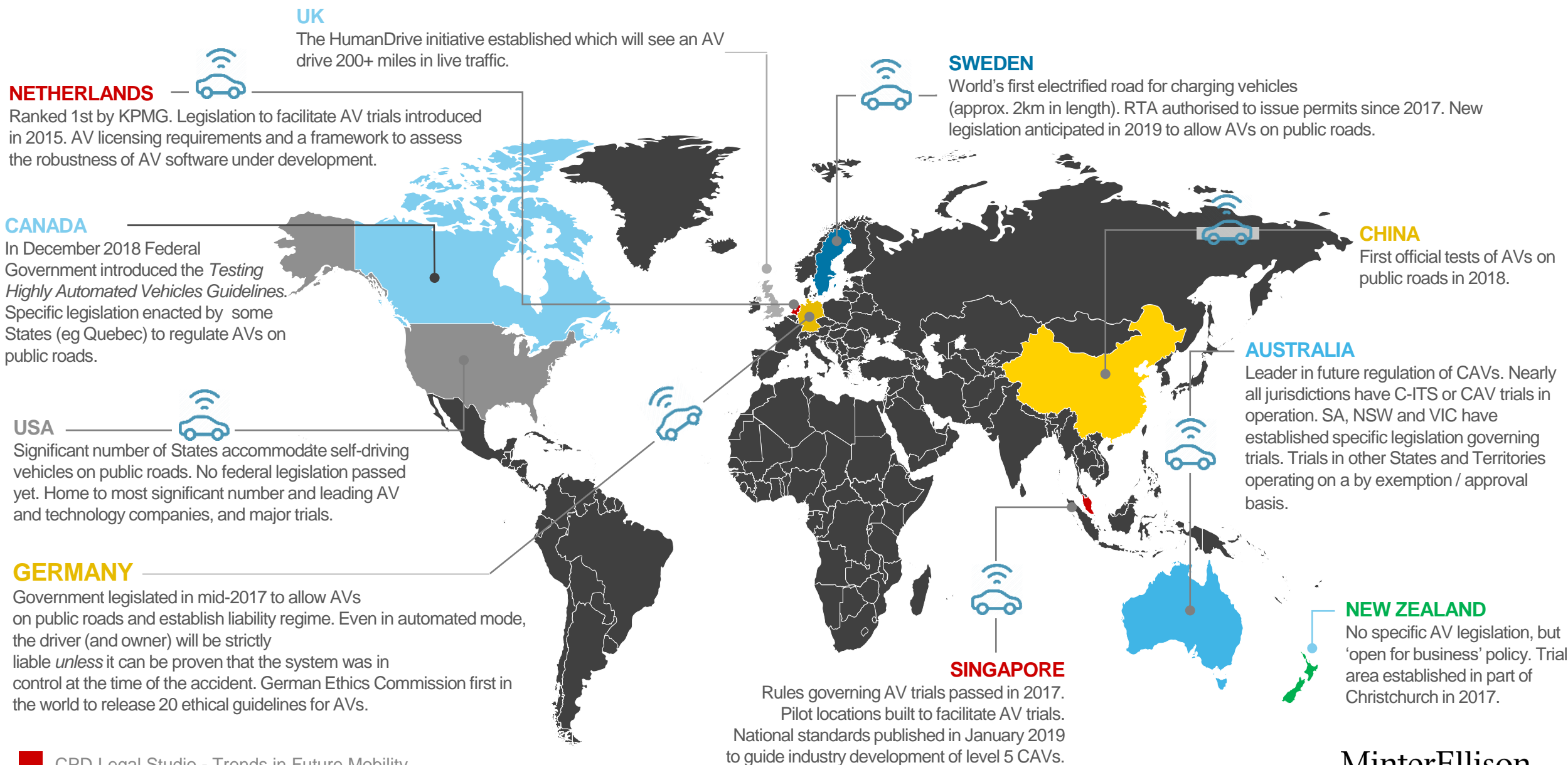
Mcity operates the world's first purpose-built proving ground for testing the performance and safety of connected and automated vehicles and technologies under controlled and realistic conditions



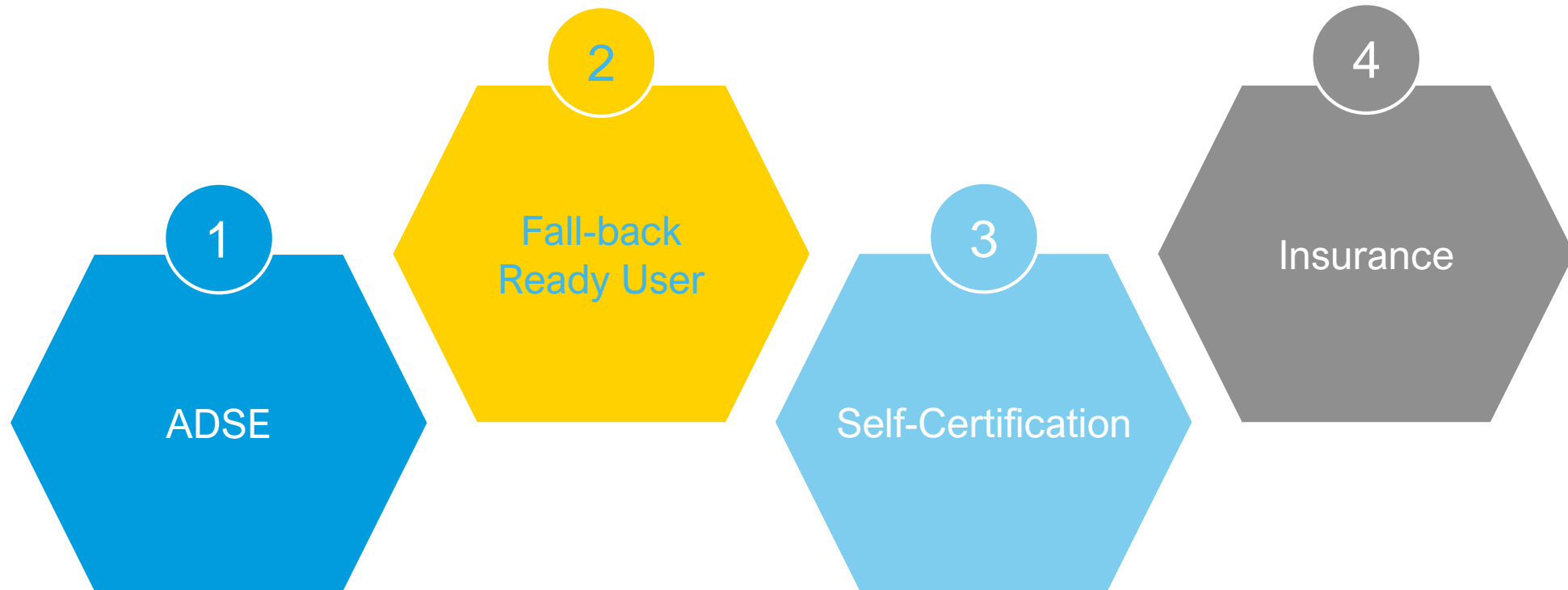


What's new in driverless mobility development?

Current trials and international developments



Australia's changing laws



Who is in control of the CAV?

For high and full automation (SAE levels 4 and 5):

NTC recommends the ADS is in control

But, carve outs / apportionment is required. For example:

- third party modifications;
- communication failures (i.e. sensors); and
- hacking or disruption by a third party.

Difficulties with conditional automation (SAE level 3) – control by ‘fall back’ user.



Lessons learnt from Uber fatality

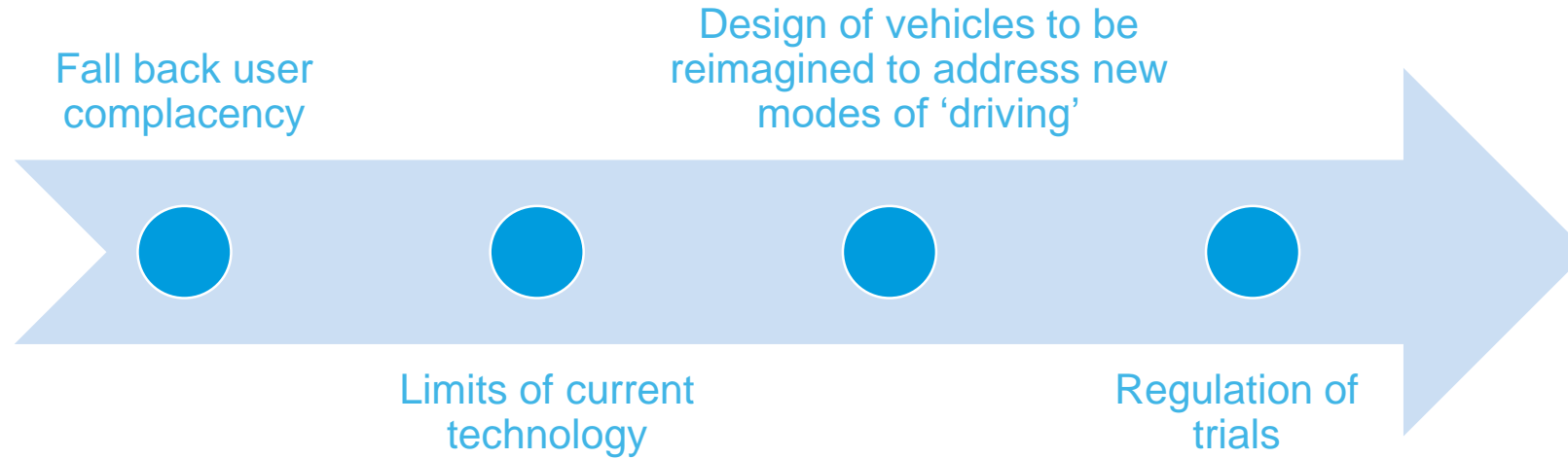


Figure from the US National Transportation Safety Board Preliminary Report (May 2018) showing the video of the self-driving system data playback approx. 1.3 seconds before impact.

Changing legal and regulatory environment

Nuro R2

SAFETY INNOVATION

Narrow Width

The vehicle body takes up less road space, making it safer for those around us

Pedestrian-Protecting Front End

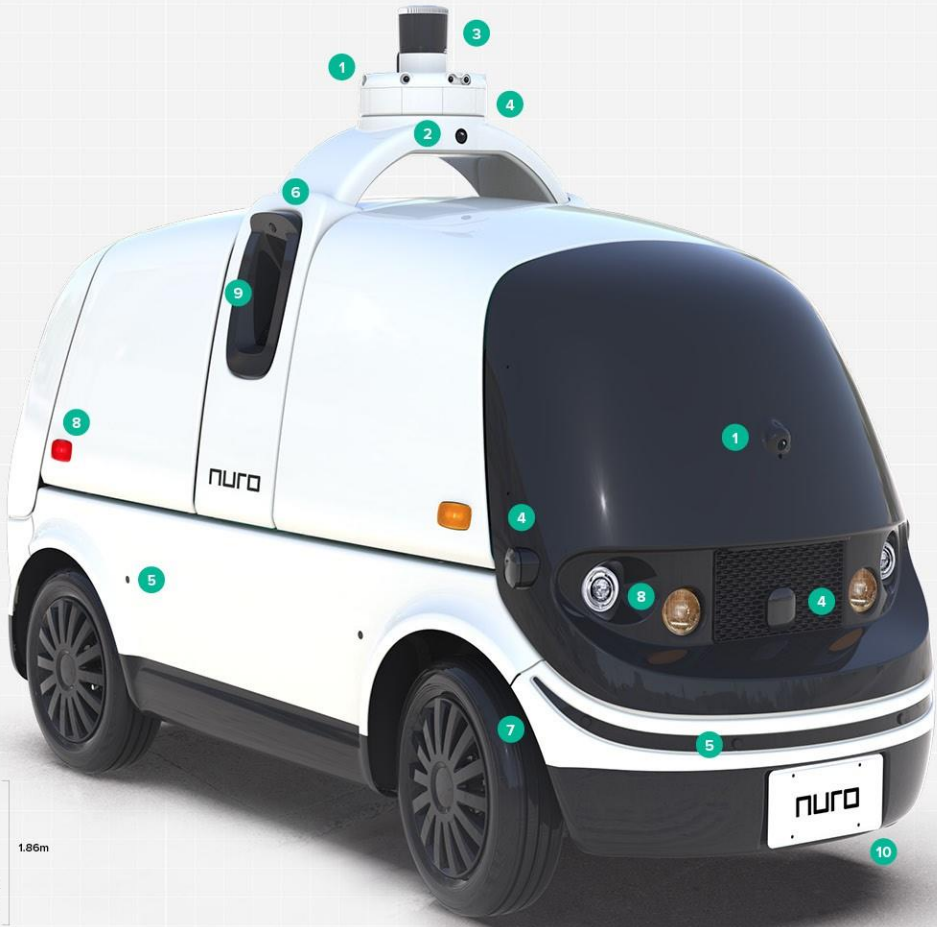
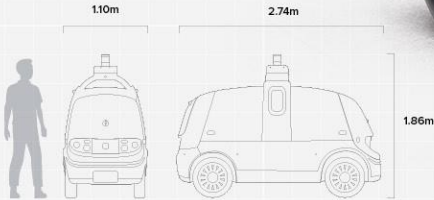
Specially designed panel at the vehicle's front absorbs energy, better protecting pedestrians

360° View

Embedded sensor placement creates redundant, simultaneous views in all directions

Curbside Delivery Doors

Customers can retrieve goods without stepping into traffic



SENSORS

- 1 360° overlapping cameras
- 2 Thermal imaging camera
- 3 Lidar
- 4 Short & long range radar
- 5 Ultrasonics
- 6 Emergency vehicle audio detection

VEHICLE EQUIPMENT

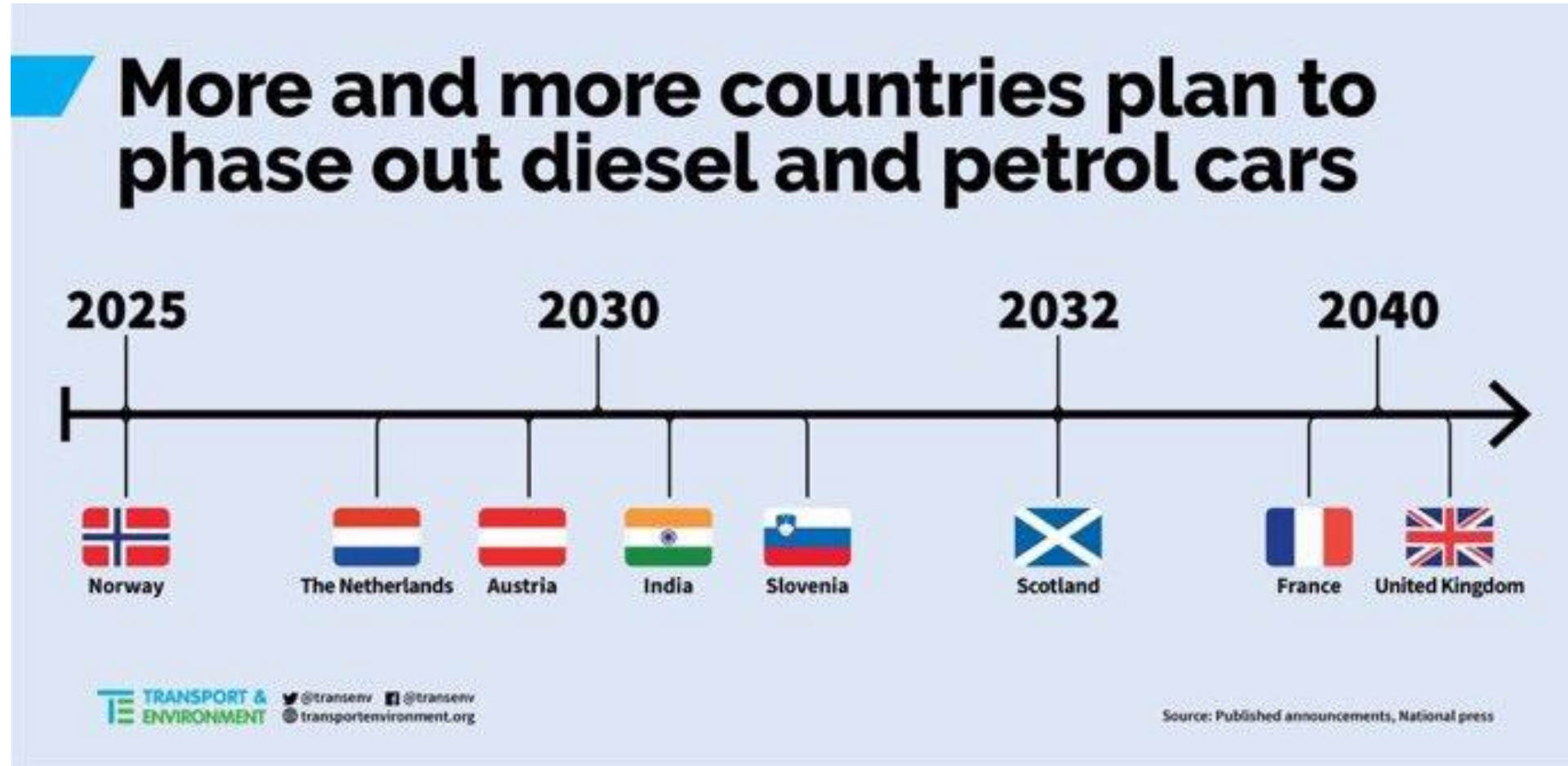
- 7 Redundant braking and control systems
- 8 Automotive lighting and signals
- 9 Touch screen for customer access or law enforcement interaction
- 10 Sound generator for pedestrian safety

VEHICLE SPECIFICATIONS

Max Speed:	25mph
Battery Size:	31kWh
Charge Speed:	L2, 6.6kWh/hr
Gross Vehicle Weight:	1150kg
Payload:	190kg
Carrying Capacity:	22.38 ft ³

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What's happening with vehicle manufacturers?





On demand private and public transport services

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Vancouver – Car sharing

Zipcar is the world's leading car-sharing network

on-demand
access to
drive cars by
the hour or
the day in
cities,
airports, and
campuses
around the
globe



NSW on demand trials

On Demand is a flexible public transport service designed to improve connections to transport hubs and popular destinations like shopping centres or hospitals.

On Demand services operating around NSW as part of a trial

NSW trials are in regional areas as well as metro



Autonomous and on demand Bus Trials

The City of Newcastle on the NSW automated shuttle bus | Similar to those in Sydney Olympic Park

Cooee and Metro Connected Bus Trials in Regional NSW





AI and big data technology to support mobility

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FUTURE OF WORK



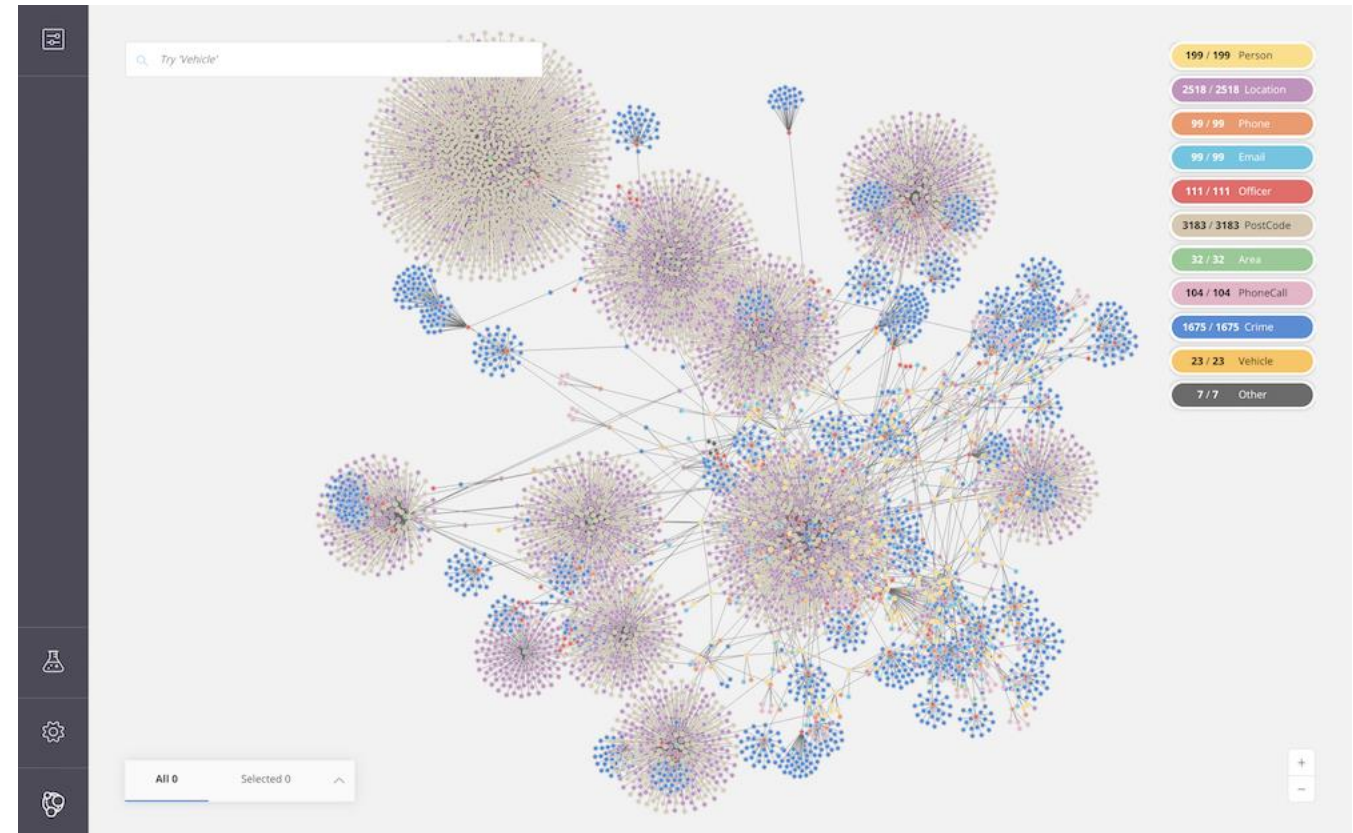
Big Data : AI, Relational and Graph Databases



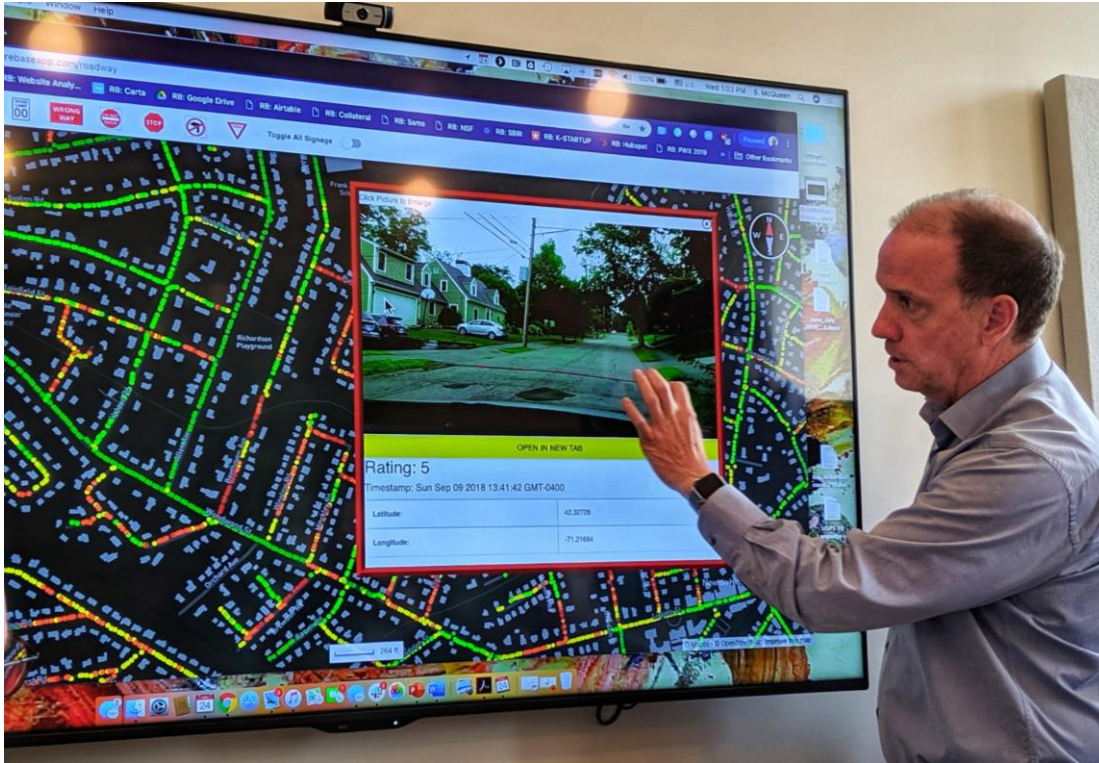
If the autonomous vehicle's AI needs to see every possible combination of light and weather conditions, it would be impossible to train it for all possible situations

But if the AI is supplied with connected, contextual information (rain *and* night, night *and* temperature), it is possible to combine information from multiple contexts and infer the next action to take (like slowing down or turning on headlights).

Graph technology connects data and defines relationships. By enhancing AI with related context, graph technology offers an effective means to empower the development of sophisticated AI applications.

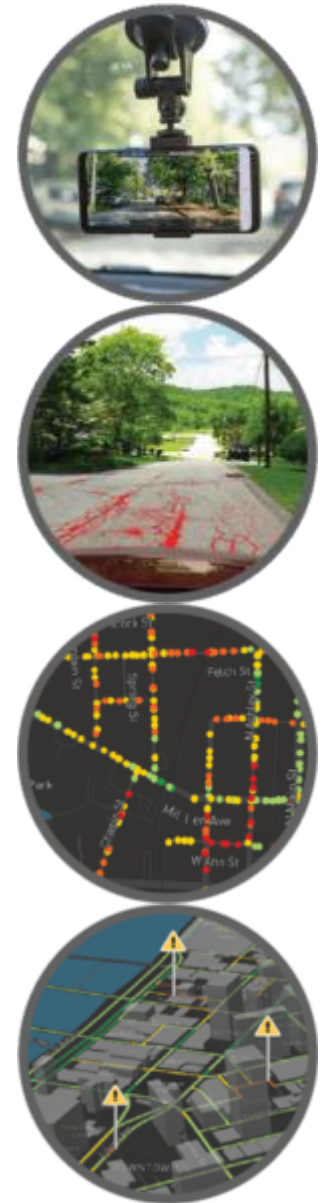


Big Data – RoadBotics & On demand maintenance



Governments and councils manually inspect their roads or use van-based services to prioritize maintenance needs

RoadBotics is providing timely, data-driven results that are objective, cost-efficient, and easy to visualize



Big Data : Connected vehicles and Insurance

Usage-based insurance policies use the vehicle's built-in modem to track your driving habits and adjust your rates accordingly with each renewal

The technology tracks distance, your aggressiveness with pedals, idle time and night driving. The companies are promising discounts of up to 40 percent, The insurance is available now in 39 states This is more convenient than other forms of usage-based insurance

You don't need to buy a separate dongle, and you can sign up through the Ford or Lincoln apps with some of the details already filled in



Australia's AI Ethics Framework

1. AI should generate net benefits
2. AI should do no harm
3. AI should comply with the law
4. AI should ensure personal information is protected
5. AI's development and use must be fair
6. AI should be transparent and explainable
7. AI processes should allow for contestability
8. Those creating and implementing AI should be accountable



How do we regulate AI?

- Suggested approaches
- Australian recommendations
- Overseas developments



Emerging best practice

Planning	Implementing
<ul style="list-style-type: none">• What is the purpose of the system?• Which principles will guide development and use of the system?• How will you demonstrate that the principles have been met?	<ul style="list-style-type: none">• Impact and risk assessments• Ethical review• Continuous monitoring• Review mechanism



Micro mobility

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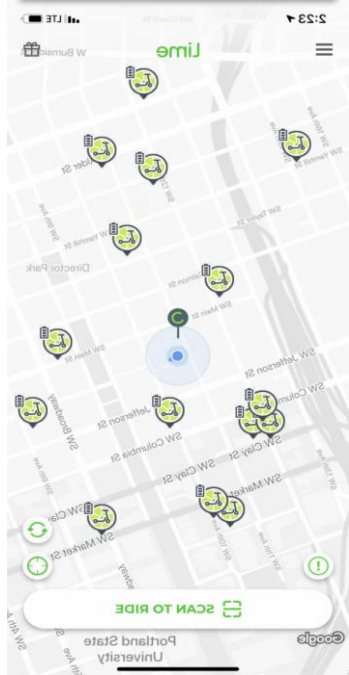
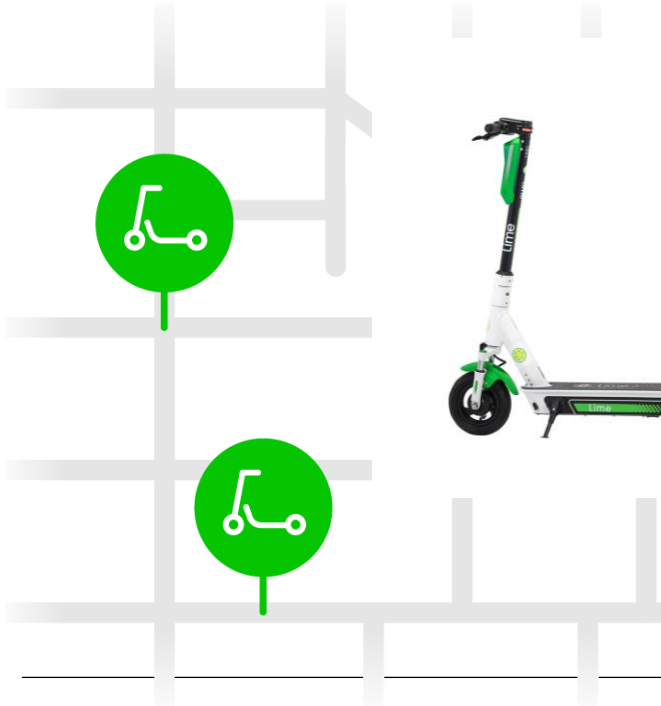
Micro and Big Data : AI Suitcase

Big Data Establishment of the Consortium for Advanced Assistive Mobility Platform, Aiming to Improve Accessibility and Quality of Life for the Visually Impaired, Through AI Suitcase Development



Basic Functions: Navigation	
1.	Optimal route planning to a destination based on location and map information
2.	Navigation through voice and haptic devices
3.	Obstacle avoidance by analyzing data from video cameras and distance sensors
Original Functions: Social Behavior and Communication	
4.	Voice to provide information on shops nearby and guide a user for shopping based on location information and other information on cloud
5.	Communication assistance by recognizing registered faces and detecting the situation surrounding them based on facial expressions
6.	Social-behavior assistance by recognizing the situation surrounding a user through video cameras and sensors e.g. stand in line

Micro mobility – new options everyday

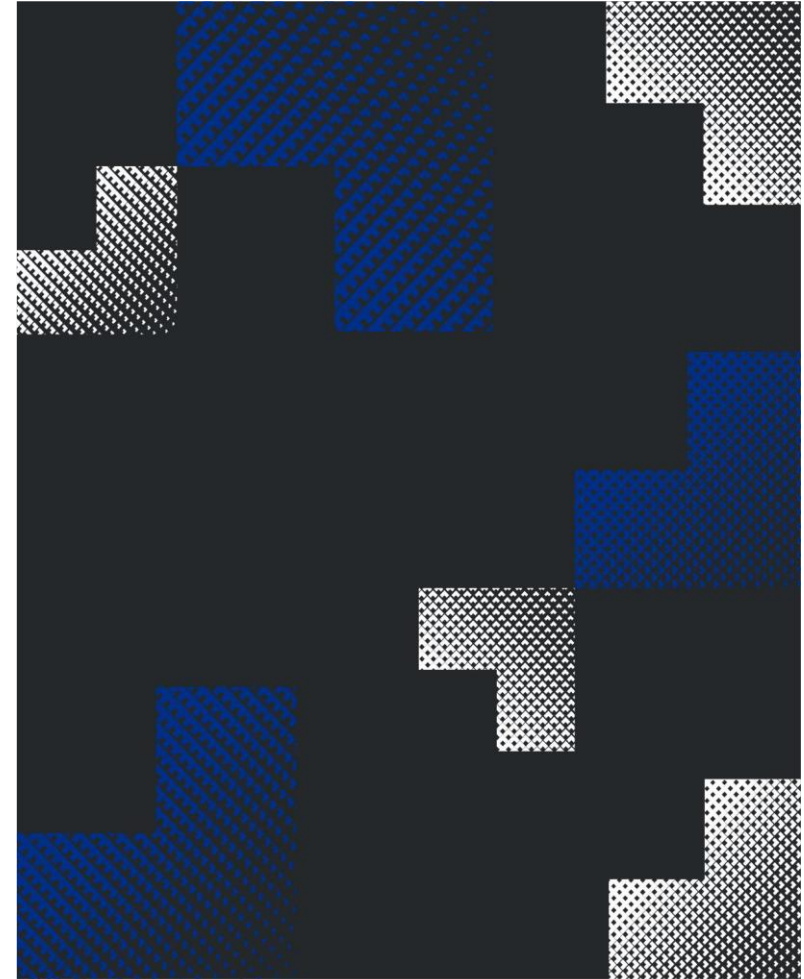


Regulatory Issues

NTC has developed a framework

Australian Design Rule exemptions

Australian Consumer protection



National
Transport
Commission **ntc**



Shaping the Future of Mobility





Questions

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